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# Safety



Live Focus System (LFS) is applied in laser processing machine. Laser protection is CLASS3 and CLASS4. Please reference to GB7247.1-2001 and take some safety protection measures.

The following should be executed:

- Operation persons should wear protection glasses.
- Connected to the ground. A valid connection to ground should be done and the resistance should be less than 10hm. CNC machine tools, LFS, sensor shell and support plate should be stable grounding.
- Please do not try to disassemble the parts of LFS. Otherwise, the LFS will be fault.
- Laser beam nozzle and the LFS sensor are integrated design. When the LFS is working, please do not touch the sensor. Otherwise will cause damage to your body.
- When cutting glossy surface metal, please notice the reflect laser beams from the metal surface. Some protection measure should be taken to avoid the body to be damaged. Preventive measures should be taken and operate carefully, to prevent burn out parts by laser beam off center axis.
- Keep the sensor and nozzle clean. Avoid the cooling water, condensed water or other foreign matter flowing into sensor; otherwise the sensor will be fault. The laser power and other controllers should meet the EMC standard and should be connect to the ground reliably.
- Sensors and electrical cabinet parts must be grounding as requirements. Processed metal artifacts should be reliable grounding.



# **Chapter 1 Overview**

# **1.1 Visual Cutting Control System Introduction**

Visual cutting control system (RDVision) is cutting system based on intelligent target recognition. This system is mainly composed of PCI motion control card and CCD industrial camera. Combined with image processing algorithm for target image feature extraction and target recognition and finish cutting work by artificial cut outline. The system operating software control card and the upper machine by Ethernet or USB interface for communication.

This system user friendly interface, stable performance, simple operation, suitable for large-format array type graphics cutting, such as trademark cutting field.

## 1.2 The composition of the visual cutting control system

Control system consists of two parts, hardware and software. Hardware equipment as shown in Figure 1.1



Project	Quantity
Control card	1 pcs
Control panel	1 pcs
LED loop lighting group	1 set
Driver board	1 pcs
Lens	1 pcs
Camera (with cable)	1 set
Brightness regulator (with cable)	1 set
Transfer fold-resistance cable	lpcs
Mechanical mounting bracket	1 set
KF3.81 socket 6P	9 pcs
KF3.81socket 5P	1 pcs
KF3.81socket 4P	3 pcs
KF3.81socket 2P	1 pcs
DP15 data cable (1.5M)	1 pcs
USB cable (1M)	1 pcs
Reticle (5M)	1 pcs
internet access cable (1M)	1 pcs

Figure 1.1

Software is RDVisionSetUp.

## **1.3 Software installation**

Software installation and system hardware configuration requirements:

(1) Running on Windows XP and above version operating system, it is recommended to use the Windows XP.

(2) CPU 586 above, it is recommended that the PIII or above PIV.

(3) It is recommended to use more than 1 G of memory.

#### 1.3.1 Start installation

Double-click the install directory RDVisionSetUp.exe icon, dialog box (Figure 1.2) will popup as follows:

**RDVision Laser Cutting Control Software Operation Manual** 



Figure 1.2

Click on the "Install" button, to extract the replication is complete, install the interface (Figure 1.3).

Language:	English 🗸
Install camera	Uninstall camera
Install USB	Uninstall USB
Locate install	path
Install	software
Ex	cit

Figure 1.3

#### 1.3.2 Driver install and uninstall

Camera driver install and uninstall:

Click [Install camera] button on the main interface (Figure 1.3), installation interface will be appeared in Figure 1.4

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Figure 1.4

Click "next":



Figure 1.5



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If the user need to uninstall the **[** camera driver **]**, click **[** uninstall camera **]** button on the main interface (Figure 1.3), will appear the interface in Figure 1.6:

Unins	tall	Driver	Package			
?	All dev	vices using	this driver will	l be removed.	Do you wish to	continue?
			<u> </u>	否(11)		

Figure 1.6

Click "yes" to uninstall the camera driver.

Controller driver install and uninstall:

Users click **[**Install USB] on the main interface (Figure 1.3), prompt to connect USB, to make sure connected USB, click "OK".

RDVisi	onSetUp 🛛 🔀
<u>.</u>	Before install, connect VSB first!
-	· · · · · · · · · · · · · · · · · · ·

Figure 1.7

And then displaying the interface as Figure 1.8 showed:



Figure 1.8

If the user need to uninstall the motherboard driver, click **(**Uninstall USB**)** on the main interface (Figure 1.3) will appears Figure 1.9:

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Figure 1.9

Click "OK" to uninstall the controller driver.

The Software installation:

When users installed the camera driver and motherboard driver, click "Install software" button on the install main interface (figure 1.3) and it will pop-up a prompt interface "Install Finish!".



Click "OK", visual cutting software installation is completed.

If the user set the installation path manually, check the option "manually locate the installation path" on the main interface (figure 1.3). Position setting interface will occur in the following installation process (figure 1.11).



浏览文件夹	? 🗙
Selected Install Path:	
<ul> <li>□ </li> <li< td=""><td>^</td></li<></ul>	^
□ → 本地磁盘 (C:) □ → 本地磁盘 (D:)	
<ul> <li>□ → 本地磁盘(E:)</li> <li>□ → ○ CD 驱动器(H:)</li> <li>□ → ○ 共享文档</li> </ul>	
<ul> <li>H→□ Administrator 的文档</li> <li>□ □ □ □ □ □ ■ ■ ■ ■ ■ ■ ■ ■ ■ ■ ■</li> </ul>	
H Microsoft Windows Network	

Figure 1.11

After choose the required path, click [OK], the program will be installed under the user setting path.

#### 1.3.3 Exit

The system software installation is completed, click "Exit" button on the install main interface (figure 1.3) to end installation process.

## **1.4 Software Features**

- 1. Compatible with AI, BMP, PLT, DXF, DST, and other graphics data format.
- 2. Can edit and typeset simple graphics, text, and import the data.
- 3. Layout and define the output sequence.
- 4. Can set the machining process and precision personally
- 5. It can realize processing path optimization function.
- 6. Suspension in the manufacturing process of processing.
- 7. According to the different requirements of processing can be set as a starting point, the work path.
- 8. Compatible with many kinds of communication mode, the user can use USB-port communication or network communication according to the actual situation.



# **Chapter 2 Software Basic Operation**

# 2.1 The main operation interface

Start the software, can see the interface as shown in the figure below. Familiar with the operating interface, the software will be used for the basis of laser processing.



[Main interface view]: The current perspective is video, display data for the camera view. If need to switch into the Machine view, simply click on the machine view, will switch to the machine perspective:

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Ditto, can also switch to the Model View.

As shown in figure: Model as the switch on the control panel module management. Each model manages the important operating parameters and related functions.

[Menu bar] : the menu bar file, edit, drawing, setup, processing, view and help seven functions menu items.

【Cutting properties bar】: mainly is the basic attribute of graphics, contains graphic location, size, model basic properties such as zoom, and processing sequence number.

[System toolbar] : toolbar buttons for the most commonly used features, most of these options from the menu bar.

[Drawing toolbar] : when the system default is located in the work area on the left. On the drawing toolbar placed often use the editing tools, can undertake various edit operation to need to edit the object.

[Control panel] : Control panel and main implementation of some commonly used operation and settings.

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# 2.2 Language settings and manufactures information

In addition to the application installation process can set the language type of software, in use process also can switch different languages.

Click "menu" - > "Help" - > "语言/Language", select the required language type, which can switch language.

Н	elp(H)		
	About RDVision		
	语言/Language	•	简体中文 繁体中文
			🗸 English
			Other

To attain manufacturer information, so that manufacturers provide a better service for you. Click [menu] -> [help] -> [About RDVision], can display manufacturer's information.

About		
Corp. Name:		
Tel:		
Fax:	000	
Addr:	000	
Web:		
RDVisionV1.0.13		ОК

In "about prompt interface" below is the current software version number. In different software version, there are differences in function or interface. Through the software version number, it can be convenient to contact and communication with manufacturer for users.

# 2.3 Page Setting

Click "menu" -> "Settings" -> "page setting", appearing the interface as the following:

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			age setting
-	17 C		Page size
	mm	850	Page width:
	mm	500	Page height:
			Keyboard
	mm	1	Adust distance:
		10	Adjust ratio:
	0	1	Adust angle:
		10	Adust distance: Adjust ratio: Adust angle:

[Page width]: view page width, size of the X wide general Settings for the machine. [Page height]: high view page, the Y wide general Settings for the machine size.

Usually, if the PC is connected to controller, the software will automatically gets the current machine working level, as the page size. Under the condition of PC is not connected to the motherboard, or the user needs to define your own page size (e.g., according to the material to set the page size), can use the page setup to reconfigure the page size.

[keyboard] : the software can be through the up and down or so key keyboard to adjust the positions of the graphics in the view.

According to a direction, moving distance = [Adjust distance];

Press the SHIFT key and press a key direction, moving distance = [Adjust ratio] \* [Adjust distance];

Press the Ctrl key and press the direction key, graphics rotation Angle = 【Adjust Angle】;

Press Ctrl + Shift and at the same time press the direction key, the graphics rotation Angle = 【Adjust Angle】\* 【Adjust ratio】

# 2.4 Import and export files

Since this software is used. RLD format file, which needs other file format when making or editing done through import, derived by save as other file format data. Import the file formats supported: DXF, ai, PLT, DST, DSB... And so on; the exported file format support: PLT.



#### <u>RDVision Laser Cutting Control Software Operation Manual</u> 2.4.1 Import File

Click on the "menu" -> "file" -> "imported", or click on the import icon, will display interface as below Figure 2.4 shown.

Choose the corresponding file, click "Open" button.

査技范围(1):PLT中目行车.plt1987.plt中留方车.plt1987.plt中富貴花开11.plt1987.plt中富貴花开11.plt1987.plt中富貴花开11.plt1987.plt中富夫法集团家.plt1987.plt中花形注集图家.plt1987.plt中花形注集图家.plt1987.plt中花形注集图家.plt1987.plt中茂形注集图家.plt1987.plt中茂水注集图案.plt1987.plt中茂水注集图案.plt1987.plt中茂水注集图案.plt1987.plt中茂水注集图案.plt1987.plt中茂水注集图表.plt1987.plt中茂水注集图表.plt1987.plt中茂形之232.plt1985.plt中荒影方部组合.plt1985.plt中荒影方部组合.plt1995.plt中常形之232.plt1995.plt中常形之232.plt1995.plt中常形之232.plt1995.plt中常形之232.plt1995.plt中常形之232.plt1995.plt中常形之232.plt1995.plt中常形之232.plt1995.plt中常形注集.plt1995.plt中常小指1995.plt中常形式1995.plt中常小指1995.plt中常小指1995.plt中常小指1995.plt中常小指1995.plt中常小指1995.plt中常小指1995.plt中常小指1995.plt中常小指1995.plt中常小指1995.plt中常小指1995.plt中常小指1995.plt中常小指1995.plt中常小指1995.plt中常小指1995.plt中常小指1995.plt中常小指1995.plt中常小指1995.plt中常小指199	导入	? 🔀
Impose 0000033.plt       Implify plt       Implify plt         Implify plt       Implify plt       Implify plt <td>查找范围(I): 🔁 PLT 🗾 🗢 🖻 💣</td> <td>·</td>	查找范围(I): 🔁 PLT 🗾 🗢 🖻 💣	·
	Imp 0000033.plt       Imp 49.plt       Imp 49.plt       Imp 1674.plt         1mp 987.plt       Imp 367.plt       Imp 367.plt       Imp 3676.plt         1mp 9876.plt       Imp 3676.plt       Imp 3676.plt       Imp 3676.plt         1mp 9876.plt       Imp 3676.plt       Imp 376.plt       Imp 376.plt         1mp 9876.plt       Imp 376.plt       Imp 376.plt       Imp 376.plt         1mp 376.plt       Imp 376.plt       Imp 376.plt       Imp 3	✓ Preview
文件名 @): Airplane.plt	文件名 (D): Airplane. plt 文件类型 (T): Supported Files1	<mark>」 ② D</mark> pen ▼ ▼ 取消

Figure 2.4

If selected "Preview", will display the image when select the file.

For vector data, the data according to the corresponding hierarchical description file format automatically imported into the RDCAM corresponding layer.

For some special file like DST/DSB will be import the current layer



导人		
查找范围(L):	DST	▼ ⇔ 🗈 📸 •
MANUTI 61. DS LSO45 DST LSO66. DST Lz215. DST MISO. DST MISO. DST SUNFLOWE. I VERONIKA. I	T ST ST	
立 计研究 00 ·	AL. 3: -1 DCT	₩ freview
文件类型(I):	Supported Files1	Upen V 文

#### 2.4.2 Export File

Click "menu" -> "file"-> "export" or click the icon, then show that export operation interface; Input the file name, then click "save" button.

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#### 2.4.3 File parameters setting

File Parameter	
Import Setting	
PLT Precision:	1016 👻
DXF Unit:	MM 🔽
Import Dxf text info	
Auto close curves	
Close error(mm):	0.1
Combine lines	
Combine error(mm):	0.1
Export Setting:	
Export Precision(%):	80
Velocity Unit:	mm/s 🔻
Ok Cance	1

[PLT Precision] According to the precision of the original PLT file to choose the appropriate import units

【DXF Unit】 Software default DXF import unit is mm. If there is an import DXF data size does not agree with the original graphics, may be caused by unit does not match. Optional data unit is mm, cm, inch, custom, when choose the custom, any user set up a unit of data in DXF file corresponding to the RDCAM software in millimeters.

[Import Dxf text info] When the user need only within the Dxf graphics information, without the need for a file in the text message, are not checked

**Curve** smooth **D** Vector file import, automatic smooth not smooth the curve of the original graphics. For original graphics itself relatively smooth or need to repeatedly adjust the best smoothing effect, are not checked, reduce import processing time. Processing it after the file imported.

[Auto close curves ] According to the close tolerance automatically checks and closed curve

[Combine lines] According to the merger of tolerance, automatic connection curve

**(**Velocity Unit **)** Speed unit is mm/SEC, m/points two kinds, we can choose according to the habits, the selected interface about speed parameter units will change accordingly.

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# RuiDa ACS

# 2.5 Basic graphics creation

#### [Node edit]

Click on the "menu" -> "Draw" -> "node editor", or click the edit toolbar , drag the mouse on the screen, click the mouse at any position, can draw the point.

#### [Line]

Click menu [Draw] -> [Line], or click Edit toolbar, drag the mouse on the screen you can draw an arbitrary line. Press the "Ctrl" key while dragging the mouse to draw horizontal or vertical line.

#### [Polyline]

Click menu [Draw] -> [Polyline], or click Edit toolbar . Drag the mouse on the screen And you can draw an arbitrary polyline.

[Bezier] Click[Draw]->[Bezier]or click the Edit toolbar. The process of drawing refers to [Polyline] process.

Difference is that when you insert the middle point and hold down the left mouse button and drag to adjust the curve control points.

#### [Rectangle]

Click menu [Draw] -> [Rectangle], or click Edit toolbar . Drag the mouse on the screen you can draw an arbitrary size rectangle. Press the "Ctrl" key while dragging the mouse to draw square.

#### [Ellipse]

Click menu [Draw]->[Ellipse], or click Edit toolbar  $\bigcirc$ . Drag the mouse on the screen you can draw an arbitrary size ellipse.

Press the "Ctrl" key while dragging the mouse to draw round.

#### [Edit text]

Click on the "menu" -> "Draw" -> "text", click edit toolbar and then click the drawing area in any position, the pop-up text input dialog box.

Choose fonts, enter text, then set the word height, the word width, word spacing, line spacing. Click [Ok].

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ext					
TrueType font:	™r Tahoma	×	Width:	50	%
O SHX font:	🚮 Fs.SHX		Char space:	0	mm
Text		4	Line space:	0	mm
			]Enable variat	ole text	
		×			
leight: 8	mm		ОК		ancel

Software also supports variable text, the so-called variable text, the text needs to change as certain rules, output processing one time, text will change automatically. System supports type text with date and serial number.

Date variables are processing the current system time of the current computer output. Software provides a variety of date formats for the user choosing.

Users can set date offset, 3 kinds: daily/monthly/yearly. Such as marking the product shelf life on product package.



Text					×
• TrueType font:	7∰r Tahoma	~	Width:	50	%
◯ SHX font:	🚮 Fs.SHX	<u> </u>	Char space:	0	mm
Text			Line space:	0	mm
			Enable variat	ole text	
			Date		~
			default[201304	16] [[03:47]	<u> </u>
			12Hour[HH:MM	[03:47:16]	l l
			24Hour[HH:MM] 24Hour[HH:MM]	][15:47] ][15:47:16]	
			American Date[ Chinese Date[2	04/16/2013 013年04月	6] 16日1
			Chinese Date T	ime[2013年	04月16 新知
			European Date	Time[16/04	/2013p]
			European Date Week Year[16/	[16.04.2013 04/2013 15)	3] :47:16] 🧔
		~	million (xi)	D[1/(10]	
5		×	Offset: D	ay 💉 0	×
Height: 8	mm	Apply	ОК		Cancel

Serial number variables can be digital serial numbers (0-9) or letters (a-z or a-z).

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<b>RDVision</b> Laser	Cutting	Control So	ftware O	peration	Manual
ILD / ISTOIL DUSCI	Chilling	0000000	100 40 0 0	peration	111000000

Text					X	
• TrueType font: • SHX font:	₽ Tahoma M Fs.SHX	<ul><li>✓</li></ul>	Width: Char space:	50 0	% mm	
Text		^	Line space:	0 le text	mm	Extend
			SerialNO Prefix Suffix Start SN Current SN SN Ind	: 0000 4: 0000 :: 1 E	×tend	<ul> <li>Enable reset</li> <li>✓ Enable prefix ZERO</li> <li>Enable SN array</li> <li>Number Space</li> <li>X: 1</li> <li>10</li> <li>Y: 1</li> </ul>
Height: 8	mm	Apply	ОК		Cancel	OK Cancel

Suppose you want to processing ABC0001DEF repeatedly, ABC0002DEF, ABC003DEF until ABC9999DEF such a set of serial number.

[Prefix]: serial number of prefix, ABC in the example is leading strings.

[Suffix]: serial number of suffix, DEF in the example is back leading strings.

[Start SN]: to specify from which serial number to start processing, case 0001 is the starting serial number.

[Current SN]: the current processing to which the serial number, can also be used to specify the current processing which serial number. If when processing a set of serial Numbers, leaks, processing in one, can be processing, by specifying the serial number instead of setting start serial number, because in some cases a set of serial number requires repeated processing, namely to after a certain number, need to return to start serial number to start processing.

[SN Inc]: to specify the serial number on the number of intervals. In the example, processing from 0001 to 9999 in turn as serial number, the increment is 1. If you just need to output an even or odd number serial number, you can set increment as 2.

[Enable reset]: when machining to reset the serial number, serial number will be automatically reset to the current serial number start serial number.

Case requires repeated processing sequence number from 0001 to 9999, therefore can specify 9999 for reset the serial number, after when processing the 9999 serial number, text will automatically change to 0001

[Enable prefix ZERO]: without enabling leading zeros, then the system will automatically remove the serial number of the first nonzero Numbers in front of zero. As the serial number of the case, if there is no can make leading zeros that ABC0001DEF will become ABC1DEF. But it is worth noting that if we want to output the sequence number is ABC1DEF, ABC2DEF until ABC9999DEF, we cannot pass will be set to start serial number 1,  $\frac{24}{81}$ 



but by eliminating, enabling leading zeros .this is because the set start serial number in a specified sequence number from which one number, also specifies the number of significant digits, such as to start the serial number is set to 1, the serial number of the change order is: 1,2,3,4,5,6,7,8,9,0,1,2,3,4,5... The serial number will not change to 10, because only one serial number of the effective bits.

[Enable SN array]: in the form of arrays, one-time processing multiple serial Numbers. Such as:

0001 0002 0003		0010 0011 0012
0006 0005 0004	after machining this batch number,	0015 0014 0013
0007 0008 0009	directly to the next set	0016 0017 0018

# 2.6 Object Selection

In the process of drawing and edit graphics, first of all is to select the object. When the object is being selected, in the center of this object will have a shaped mark " $\times$ ", and surrounded by eight control points.

Click menu [Draw] -> [Select], or click Edit Bar, switch to status "Select". Under this status, you can select object. The following are five kinds of method of selecting:

- Click menu [Edit] -> [Select All] (Shortcuts Ctrl+A), select all objects.
- Click to select single object



• Select object using select box

Press the mouse and drag, as long as the box come into contact with the object will be selected.

◆ Increased select object/minus select object

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Increase select: Press "Shift" key, click or box select to increase select object. Minus select: Press "Shift" key, click or box to select the selected object.

# 2.7 Object Transformation

Transformation of object mainly include: object location, orientation and size, but not change the basic shape of the object and its characteristics.

Transformation of object for users, provides a convenient user interface. User can mirror and rotation through

within the draw toolbar.

You can also use the Object Properties toolbar, transformation tools to transform and copy the graphics.

X 0.14	mm \leftrightarrow 25.232	mm 100	% _ =	
Y -0.42	mm 🕇 38.69	mm 100	% 🔳 🆽	Process NU: 1

#### 2.7.1 Object Mirror

Object image is flip the selected object in the horizontal or vertical direction.

Click Edit Bar 4, flip the selected object horizontal.

Click Edit Bar 🚽 , flip the selected object vertical.

Or through mirror transform tools, to mirror at horizontal and vertical direction, and copy.

#### 2.7.2 Object Rotation

Click Edit Bar<sup>O</sup>, will pop up the dialog of rotate angel setting.

Set rotate angle precisely and click the button **[**OK**]**.

Rotate	
Rotate angle(deg) 45	
Ok Canc	el

If you want to drag rotation, set rotate angle 0, and then "OK".

Dragging the mouse to adjust the rotate angle, in the dragging process, there will be followed by rotating  $\frac{26}{81}$ 



wire-frame outline.



Or directly enter the rotation angle in the Object Properties toolbar.

#### 2.7.3 Place Object

Place the object is to facilitate the view or orientation. The following tools are provided by software:

12 , selected object will be placed in the center of the page, that is, the object center coincides with the center of the page.

, selected object will be placed on the page left, upper right, lower right, lower left, upper left 2 corner of the object, upper right, lower right, lower left and upper left corner, top right, bottom right, bottom left corner of coincidence.

# 2.8 Object Alignment

Select multiple objects, click aligning toolbar bar

NHX H	3 3	Ū⊘	<u>∎</u> ≬	₽	₿	<b>}</b> ⊷€	¥		I	$\oplus$	
I	ncludir	g:									
	엄		Left	alignr	nent, I	Right a	alignr	nent, '	Гор а	lignme	ent, Bottom alignment
€	} ₿	H Ve	ertical	cente	r align	iment,	Horiz	zontal	cente	er aligr	nment, center alignment
									:	27 / 81	
							© 20	16 Ruida	a Techn	ology. All	Rights Reserved.



Horizontal equidistance, Vertical equidistance

Same width, Same height, Same size.

The align benchmark object:

For pressing "Shift" to select single object one by one, the last object is the benchmark object. For box select, the benchmark object is the object which curve number in the last.

### 2.9 Object View

**Move:** Click menu [Edit] -> [Move], or click . Then hold down the left mouse button in the drawing area, and drag pan.

**Zoom Out:** Click menu [Edit]-> [Zoom Out], or click . Each click it, the drawing area zoom out once. Move mouse to the drawing area and click, each click, mouse position as center drawing area zoom out once.

**Zoom In:** Click menu [Edit] -> [Zoom In], or click mouse to the drawing area and click, each click, mouse position as center drawing area zoom in once.

**View Select:** Click menu [Edit] -> [View Select], or click . Move the mouse to the drawing area, hold down the left mouse button and drag, a dash border box will show in the drawing area, release mouse button, then the region in the dash border box will display in the drawing area with the largest proportion.

View Page Frame: Click menu [Edit] -> [View Page Frame], or click . The page frame will full display.

**View Data Frame:** Click menu [Edit] -> [View Data Frame], or click

View Feature Data: Click menu [Edit] -> [View All], or click .Feature data will be display.

#### 2.10 Important Tool

Here are some frequently used tools. Using these important tools, can make the current document in the graphics more orderly, and make the processing of output faster.

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#### 2.10.1 Manual sorting and the set of cutting point and the cutting direction

Software provides users a convenient tool for the manual sorting. Select  $[Edit] \rightarrow [Set cutting property]$ . Cutting property dialog box will pop up. All with manual sorting, and cut points, cutting the direction of the settings in this dialog box can be completed.



Show Path: Firstly, check the "show path", it will display the current graphics cutting order and the cutting direction.

Change the direction of processing

Click the "edit" / "set cutting direction", cutting direction into the edit mode. Then double-click on any position on the selected graphic.

Change the cutting point: Click the [edit] / [setting] cutting, cutting point into the editor mode.

Then select to edit the curves, the node at the point want to set a cut double-click can complete cutting point changes.

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#### <u>RDVision Laser Cutting Control Software Operation Manual</u> 2.10.2 Curves Smooth

For some poor precision of curve, their graphics, curve smoothing can make the graphic more smooth, processing more smoothly.

Click menu [Handle] -> [Curves Smooth], the following dialog box is appears.



Drag smoothness, click **(**Apply **)** button, the screen will be displayed before the smooth and smooth curve, easy to compare.

The black curve is the original curve, after the red curve is smooth curve.

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**RDV**ision Laser Cutting Control Software Operation Manual



You can view the graphics with drag mouse.

You can zoom in/zoom out the graphics with scroll wheel.

Click button [FullFrame], graphics will shown in the dialog box for largest.

After get satisfied smoothing effect, click button [Apply], curves will processing smooth according to smoothness settings.

Select "Direct smooth", you can use another smoothing method.

The choice of smoothing method should be changed with the needs of the actual graphic.

#### 2.10.3 Check Closure

Click menu [Handle] -> [Curve auto close], or click System Bar , the following dialog box appears.



Setting close error	
Close error(mm): 0.1	
✓ Force to close	
Ok Cancel	

**Close error**: When distance from the starting point to ending point less than close tolerance, automatic closing of the curve.

Force to close: Mandatory closure of all selected curves.

#### 2.10.4 Remove the Overlap

Click menu [Handle] -> [Delete overlap], or click , the dialog box appear.

Delete overlap lines	×
Enable Overlap error	
Overlap error(mm): 0.001	
Ok Cancel	

Under normal circumstances do not select the "Enable Overlap error". Removing the overlapping lines when two lines are compared to a good degree of coincidence. If you need to delete overlapping lines, you should select "Enable Overlap error", and set overlap error. Generally do not overlap error set too large, so as to avoid accidental deletion.

#### 2.10.5 Combine Curve

Click menu [Handle] / [Combine Curve], or click , the following dialog box appears.



Setting combine error	×
Combine error(mm): 0.1	
Ok Cancel	

The software automatically merges curves in the selected curves, when these curves merge tolerance is less than the setting of combine error.

#### 2.10.6 Data Check

After the selected graphic to check, click the [menu] - > [Handle / [data check], or click toolbar icon  $\mathbb{E}$ , the system will appear the following interface

Check close		Close check end Find unclose curves:3	
Auto close	Error(mm): 0.01	Self-cross check end Find self-cross curves:1 Cross check end Not find cross curves Overlap check end	
Check self-cross			
Check cross		Not find overlap lines	
Check overlap			
Enable error	Error(mm): 0.01	Check	

Data checking, integrates the closure checking, since the cross check overlap, cross check and data checking. Users can choose according to need to check the item, after data detected problem, in the dialog box on the right side tip problem has been detected and at the same time will question the graphics in the selected state. Repeated checking -> eliminate errors -> check process, until all the data are conform to the requirements of the processing.



#### <u>RDVision Laser Cutting Control Software Operation Manual</u> 2.10.7 Generating parallel lines

Selected to generate parallel lines of the data, click the [menu] -> [handle] / [generated parallel lines], or click the

toolbar

Offset po	ly		×
Offset(mm):	0.1 mm	Delete artwork	
⊙ In	Out	🚫 Auto In/Out	
	Ok	Cancel	

Red line is the original graphics, green line is the inward graphics.



#### 2.10.8 Model Auto Hide

In feature edit mode, hidden the cutting data; in cutting edit mode, hidden the feature data.



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# **Chapter 3 System Settings**

Before output graphics, required to determine whether the system settings are correct. Click menu [Config] -> [System Setting]



# 3.1 General settings

Soliei di Seccings Syst					
Axis Mirror			Cut parameters		^
<ul> <li>✓ Axis X Mirror</li> <li>✓ Axis Y Mirror</li> </ul>			Idle speed(mm/s)	200.000	
			Idle Acc(mm/s2)	3000.000	
			Start speed(mm/s)	20.000	
Small circle speed limit		1	Min Acc(mm/s2)	400.000	
			Max Acc(mm/s2)	3000.000	
Diameter(mm) Speed(mm/s)		Cutting mode	Normal Cutti		
1.100	0 25.000		Acc Mode	S mode	_
3.100	40.000 45.000		Home para		
4.100		10000	Home speed(mm/s)	20.000	
5.100 50.000 6.100 55.000		Auto home X	Yes		
		Auto home Y	Yes		
<					
Add	Delete		pen Save R	ead Write	6

#### **Axis Mirror**

Generally, axis direction mirror is setting based on the machine actual location of limit.

The default coordinate system is Descartes coordinate system; usually the zero point is in the bottom left. If the zero point is on the upper left, then X-Axis do not need to mirror, but Y-Axis need to mirror.

If the zero point is on the upper right, then both X-Axis and Y-Axis are all need to mirror.

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One simple method is to check the coordinate arrow position in the graphical display area according with the machine actual origin position. If not, you should modify the direction mirror.

#### **Small Circle Speed Limit**

On processing work, the software automatically determine whether the current round need to limit speed ,then according to the diameter size of the circle to determine the speed. If parameter is proper, the small circle cutting effect will be greatly enhanced. Click button [Add], [Delete], [Modify] to configuration.

The speed rule of small circle is less than the speed of the rules limiting list of small round circle of minimum radius, output as the corresponding speed of minimum radius circle.

If the speed greater than maximum speed limit lists the speed round, the speed only associated with the speed of the layer.

If the speed is in the list, set the output speed as list.

If the request received by limiting layer parameters faster than the setting speed in the layer, output as the layer speed.

#### • Add backlash

Click the "Add" button, the screen will pop up the following screen.

Small circle speed l	<
Diameter(mm)	
Speed(mm/s)	
Ok Cancel	

Set speed and diameter; click "OK", the value to be inserted into the list of backlash.

#### • Modify backlash

Double-click the left mouse button scanning (reverse backlash) need to modify the small circle parameter, then the pop-up screen shown as below:



In the interface, you can modify the current speed of the corresponding backlash.

• Remove backlash

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#### **User Parameters**

**Idle speed**: this parameter decides the max. speed of all lines not emitting beams during the operation of the machine. This parameter should not be lower than the lower of the jump-off speed of the X-axis and Y-axis and not exceed the higher of the max. speed of the X-axis and Y-axis, if the user setting is illegal, the controller will automatically take this parameter in the above-mentioned rang; A higher idling speed can shorten the operation time of the entire figure, while excessively higher idling speed may cause dithering of the tracks, therefore, you should take all relevant factors into consideration when setting.

**Idle Acc:** The acceleration speed of idle walking, matching to the idle speed, if you set too slow, the actual speed may not reach the setting value; if too fast, the mechanical structure may not withstand and cause to dithering. Generally, the idle acceleration is a little bit higher than the cutting acceleration.

Cutting Acc: the acceleration of cutting speed (cutting speed is the layer speed of the layer parameters).

**Turning speed**: the minimum speed at the turning corner in cutting process. You can reduce the turning speed properly when processing the jagged material.

**Turning Acc:** it should match the turning speed.

**Cutting mode:** there are 3 kinds of cutting mode: precision cutting, fast cutting, ultra-fast cutting. The user can choose it according to the actual applications.

**Home speed:** This parameter determines the machine speed of returning to origin. When the machine is larger breadth, to set the higher reset speed, but cannot too larger.

X, Y, Z, U Auto home: All the single axis can be set whether should reset when power-on.

**Delay before feed**: when using the feeding device, a single delay before feeding, the user can arrange such as sorting material at this time.

**Delay after feed**: refers to material feeding device to reach the designated position, which need stability for a period of time before processing.

Backlash X, Y: compensate the backlash caused by the machine drive.



# 3.2 System Info

Setting			
General settings	System Info		
-			
		Vendor password:	Input
		Mainhaand consists	
		Mainboard Version:	
			Read
			 Upgrade
			Chee
			Close

For the information on the controller operation, manufacturers need to enter password to view parameters.



Setting	
General settings System Info	
Total on time(hour:min:s): Total processing time(hour:min:s): Previous processing time(hour:min:s:ms): Total laser on time(hour:min:s): Total processing times: X Total traval(m): Y Total travel(m): Mainboard version:	
	Read Upgrade Close

Total on time: The total time of motherboard working

Total processing time: The total time of processing, including the time of jump moving.

Previous processing time: The time of the last processing

Total laser on time: The time of the laser processing

Total processing times: The number of completed processing, not include the processing forcing to end.

**X total travel**: The total travel of motor X.

Y total travel: The total travel of motor Y.

Mainboard version: The version of the current controller.

The function of upgrades:

If the board has additional features, the manufacturers will provide the update file (\*. bin format), the user can load the upgrade file to upgrade the motherboard. After upgrading, you need to click on the control panel "Reset" button reset the motherboard before normal use.



# **Chapter 4 Camera Management**

### **4.1 Camera parameters**

Click [camera para] on the operation panel button, can appear the following camera parameters Settings dialog

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Camera parar	n				
Contrast:		0	-	þ.o	%
Gain:			0_	93.0	%
G Gain:	-0			13.0	%
B Gain:	-0			13.0	%
Saturation: *				80.0	%
Explosure: -				26.0	%
Continuous	AE		Target:	50.0	%
1 Speed:	ation 100.0	mm/s	Power:	30.00	%
<b>1</b> Speed:	ation 100.0	mm/s	Power:	30.00	%
<b>1</b> Speed:	ation 100.0	mm/s	Power:	30.00 Calibration	%
<b>1</b> Speed: <b>2</b> Width:	100.0 100.0	mm/s	Power: Cut cross	30.00 Calibration 100.0	%
2 Width: Speed:	ation 100.0 100.0 100.0	mm/s ( mm mm/s	Power: Cut cross Height: Dot power:	30.00 Calibration 100.0 30.00	% 
2 Width: Speed: Go scale	ation 100.0 100.0 100.0 Dot p	mm/s mm mm/s para	Power: Cut cross Height: Dot power: Dot	30.00 Calibration 100.0 30.00 Correct	% 
Camera Calibr     Speed:     Width:     Speed:     Go scale     Redo 1st :	ation 100.0 100.0 100.0 Dot p step Cut	mm/s mm mm/s para	Power: Cut cross Height: Dot power: Dot	30.00 Calibration 100.0 30.00 Correct	% 
Camera Callor     Speed:     Go scale     Redo 1st s     Manually o	ation 100.0 100.0 100.0 Dot p step Cut	mm/s mm mm/s para cross ffset(No	Power: Cut cross Height: Dot power: Dot	30.00 Calibration 100.0 30.00 Correct	%         
Speed:     Go scale     Redo 1st :     Manually o     X:	ation 100.0 100.0 100.0 Dot p step Cut correct o 0.000	mm/s mm mm/s para cross ffset(No	Power: Cut cross Height: Dot power: Dot	30.00 Calibration 100.0 30.00 Correct	% 
Camera Callor     Speed:     Speed:     Go scale     Redo 1st s     Kanually o     X:     Ratio:	ation 100.0 100.0 100.0 Dot p step Cut correct o 0.000 1.000	mm/s mm mm/s para (ross ffset(No mm	Power: Cut cross Height: Dot power: Dot ot recommender Y:	30.00 Calibration 100.0 30.00 Correct :d) 0.000	% nm %

The adjustment of the camera on the hardware mainly by adjusting the aperture and focal length to adjust the quality of the image but the camera is installed, can't adjust. Usually adjust the environment light.

The camera parameters adjustment in the software:

Contrast: Mainly through adjust the background color and contrast material color difference to fine image quality. Gain: the brightness of the image magnification.

Exposure: the longer the exposure, the higher of the image brightness.

Click **Explosure:** can perform automatic expose operation.

"Contrast" and "gain" are both to deal with image data. So when image is in dim, firstly adjust the light source (lamp on the camera )and [Exposure], if still cannot get the desired effect, to adjust brightness, contrast, gain.

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Stabilization time: stability time associated with the machine, the machine inertia large, after the high speed movement stability will take a long time. When you take a photo and needs a stable vision. Recommended value is 300 milliseconds.

Threshold: when user extracts the characteristic curve, you can set three options (Low\Medium\High) for you. It can control the density of characteristic curve. The lower the level, the more the lines.

# 4.2 Camera Calibration:

#### 4.2.1 Cross Calibration

Camera paran	n				
Contrast:		-0		þ.o	%
Gain:				93.0	%
G Gain:	-0			13.0	%
B Gain: -	-0			13.0	%
Saturation: 🗂			0	80.0	%
Explosure:	0			26.0	%
Continuous	AE		Target:	50.0	%
Rotate angle Camera calibr Speed:	: 0 : 0 • ation 100.0	mm/s	Camera fixed Power:	mode 30.00	%
Rotate angle Camera calibr Speed:	: 0 • : 0 • ation 100.0	mm/s	Camera fixed Power: Cut cross	mode 30.00 Calibration	% 1
Rotate angle Camera calibr Camera calibr Speed: Width:	: 0 • : 0 • ation 100.0	mm/s	Comera fixed Power: Cut cross Height:	mode 30.00 Calibration 100.0	% 1 mm
Rotate angle Camera calibr Camera calibr Speed: Width: Speed:	: 0 : 0 • ation 100.0 100.0	mm/s	Contraction Hode Camera fixed Power: Cut cross Height: Dot power:	30.00 Calibration 100.0 30.00	% 1 mm
Rotate angle Camera calibr Camera calibr Speed: Speed: Go scale	: 0 • • • • • • • • • • • • • • • • • •	mm/s mm mm/s ara	Content index Camera fixed Power: Cut cross Height: Dot power: Dot	mode 30.00 Calibration 100.0 30.00 Correct	% 
Rotate angle Camera calibr Camera calibr Speed: Width: Speed: Go scale Redo 1st s	: 0 • : 0 • ation 100.0 100.0 100.0 Dot para	mm/s	Comera fixed Power: Cut cross Height: Dot power: Dot	mode 30.00 Calibration 100.0 30.00 Correct	% n %
Rotate angle Camera calibr Camera calibr Speed: Width: Speed: Go scale Redo 1st s	: 0 : 0 • ation 100.0 100.0 100.0 Dot pa step Cut of	mm/s mm mm/s ara	Content index Camera fixed Power: Cut cross Height: Dot power: Dot	mode 30.00 Calibration 100.0 30.00 Correct	% nm %
Rotate angle Camera calibr Speed: Width: Speed: Go scale Redo 1st s	: 0 • • • • • • • • • • • • • • • • • •	mm/s mm mm/s ara fset(No	Contended for the contended fo	mode 30.00 Calibration 100.0 30.00 Correct d)	% n %
Rotate angle Camera calibr Camera calibr Speed: Width: Speed: Go scale Redo 1st s Manually c X:	: 0 : 0 ation 100.0 100.0 100.0 Dot pa step Cut of 0.000	mm/s mm mm/s ara ( cross fset(Nc mm	Cont cross Cut cross Unit cross Dot power: Dot Dot Vt recommende Y:	mode 30.00 Calibration 100.0 30.00 Correct d) 0.000	% mm %



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**[Speed]** : In the process of camera calibration, laser head moving speed or when cutting cross or dotting.

**[Power ]** : The camera calibration power when processing.

**[Cut Cross]** : Click the "cross cutting", the laser will quickly cut a cross.

**[Camera Distance Calibration]**: Cut a cross, then move the camera view cross center to coincide with the cross center, click "camera calibration". System will calculate the offset from camera view center to the center of the laser head.

#### 4.2.2 Dot Calibration

Camera para	m				
Contrast:	_	-0		þ.o	%
Gain:			0	93.0	%
G Gain:	-0-			13.0	%
B Gain:	-0-			13.0	%
Saturation: *				80.0	%
Explosure:		-		26.0	%
Continuou	s AE		Target:	50.0	%
<b>1</b> Speed:	100.0	mm/s	Power:	30.00	%
Speed:	100.0	mm/s	Power: Cut cross	30.00 Calibration	% 1
1 Speed: 2 Width:	100.0	mm/s	Power: Cut cross Height:	30.00 Calibration 100.0	% ] 
1 Speed: 2 Width: Speed:	100.0 100.0 100.0	mm/s mm mm/s	Power: Cut cross Height: Dot power:	30.00 Calibration 100.0 30.00	% 1 mm %
1 Speed: 2 Width: Speed: Go scale	100.0 100.0 100.0	mm/s mm mm/s para	Power: Cut cross Height: Dot power: Dot	30.00 Calibration 100.0 30.00 Correct	% 1 mm %
<ol> <li>Speed:</li> <li>Width: Speed:</li> <li>Go scale</li> <li>Redo 1st</li> </ol>	100.0 100.0 100.0 Dot p	mm/s mm mm/s para	Power: Cut cross Height: Dot power: Dot	30.00 Calibration 100.0 30.00 Correct	% 
<ol> <li>Speed:</li> <li>Width: Speed:</li> <li>Go scale</li> <li>Redo 1st</li> <li>Manually</li> </ol>	100.0 100.0 100.0 Dot p step Cut	mm/s mm mm/s para	Power: Cut cross Height: Dot power: Dot	30.00 Calibration 100.0 30.00 Correct	%             
1 Speed: 2 Width: Speed: 6 scale 3 Redo 1st 4 Manually X:	100.0 100.0 100.0 Dot p step Cut correct c 0.000	mm/s mm mm/s para cross offset(No mm	Power: Cut cross Height: Dot power: Dot ot recommende Y:	30.00 Calibration 100.0 30.00 Correct ed) 0.000	% 

**(Width )**: The width of the camera view, after camera installed, users fill in according to the actual data, it would be larger than the actual value.

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- **【Height 】**: The height of the camera view, after camera installed, users fill in according to the actual data, it would be larger than the actual value.
- **[Interval]** : Emitting time when laser dotting a point.
- **[Space]** : Set the distance between two points.
- **(Dot)**: Click on the "Dot" button, the system will be based on user fill in the camera view the size, print out the M \* N could be covered with the camera point of view.

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		•		•		•	*	*	•		•				•	•	•	•	•	•	•	•	Contrast: þ.0
											•												Gain:093.0
																2							G Gain: 13.0
			10																				B Gain: 13.0
			*	*		*			•		•	1			•	•	•	•	•	•	•	•	Explosure:
	-		*				•			•	•	·		·	•	•	•	•	•	·	•	·	Continuous AE Target: 50.0
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L																							Mark Reacted and a million of the
																							Wait time(ms): 0 Color mode Rotate angle: 0  Camera fixed mode
		Ċ	•	•	•	•	•	8	·	·	•	ŀ	•	•	÷	•	•	·	·	•	·	•	Wait time(ms): 0 Color mode Rotate angle: 0 Camera fixed mode
		:	•					•	:	:		•		:	:	:	:			:	:	•	Wait time(ms): 0 Color mode Rotate angle: 0 Camera fixed mode Camera calibration 1 Speed: 100.0 mm/s Power: 30.00
		•	•			•		•				• • •										•	Wait time(ms): 0 Color mode Rotate angle: 0 Camera fixed mode Camera calibration 1 Speed: 100.0 mm/s Power: 30.00 Cut cross Calibration
	•	•	•	•	•			•															Wait time(ms): 0 Color mode Rotate angle: 0 Camera fixed mode Camera calibration 1 Speed: 100.0 mm/s Power: 30.00 Cut cross Calibration 2 Middle 100.0 mm Height: 100.0
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	•	•	•	•	•	•	•	• • • •	•	• • • •				•	· · ·				· · ·	· · ·	· · ·		Wait time(ms): 0 Color mode Rotate angle: 0 Camera fixed mode Camera calibration 1 Speed: 100.0 mm/s Power: 30.00 Cut cross Calibration 2 Width: 100.0 mm Height: 100.0 Speed: 100.0 mm/s Dot power: 30.00 Constale Dot nata
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ACCOUNT OF A	•	•	•	•	•	· · ·	•		•	•				· · ·		•	•	· · · ·	· · · ·	· · · ·	· · · ·		Wait time(ms): 0 Color mode Rotate angle: 0 Camera fixed mode Camera calibration 1 Speed: 100.0 mm/s Power: 30.00 Cut cross Calibration 2 Width: 100.0 mm Height: 100.0 Speed: 100.0 mm/s Dot power: 30.00 Go scale Dot para Dot Correct 3 Redo 1st step Cut cross
and		• • • • •	• • • • •	· · · ·	• • • • •	· · ·			• • • • • • •	• • • • • •			· · · ·	• • • • • •	•	•		• • • • • • •	• • • • • • • • •	••••••	• • • • • • •		Wait time(ms):       0       Color mode         Rotate angle:       0       Camera fixed mode         Camera calibration       1       Speed: 100.0       mm/s       Power: 30.00         Cut cross       Calibration         2       Width:       100.0       mm       Height:       100.0         Speed:       100.0       mm/s       Dot power:       30.00         Go scale       Dot para       Dot       Correct         3       Redo 1st step Cut cross       4       Manually correct offset(Not recommended)
Contraction -		•	• • • •	· · · · · · · · · · · · · · · · · · ·	•		•		• • • • • •		· · · ·		· · · ·	• • • • • •	· · · · · · · · · · · · · · · · · · ·		•		· · ·		· · · ·		Wait time(ms): 0 Color mode Rotate angle: 0 Camera fixed mode Camera calibration 1 Speed: 100.0 mm/s Power: 30.00 Cut cross Calibration 2 Width: 100.0 mm Height: 100.0 Speed: 100.0 mm/s Dot power: 30.00 Go scale Dot para Dot Correct 3 Redo 1st step Cut cross 4 Manually correct offset(Not recommended) X: 0.000 mm Y: 0.000
and a second sec		•		• • • • •			•		• • • • • •				• • • • • •			•	· · · ·		· · · · · · · · · · · ·	· · · · · · · · · · · ·	· · · · · · · · · · · ·		Wait time(ms):       0       Color mode         Rotate angle:       0       Camera fixed mode         Camera calibration       1       Speed: 100.0       mm/s       Power: 30.00         Cut cross       Calibration         2       Width:       100.0       mm       Height:       100.0         Speed:       100.0       mm/s       Dot power:       30.00         Go scale       Dot para       Dot       Correct         3       Redo 1st step Cut cross       4       Manually correct offset(Not recommended)         X:       0.000       mm       Y:       0.000         Ratio:       1.000       <<

**Correct** Laser puts lattice points in the middle of camera visible area, click "correction" button, the camera calibration can be realized manually. The following figure:

提示	×
理论校正点数=456,实际校正点数=454,是否手动修正	?
是(Y) 否(W)	

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3							-				•							•					Process Model	
3											•							·					X.50 205	
S											.							-					Camera para	
																	7.03	1027					Camera param	
1	•	•	*	•	•	•	•	•	•		•	•	•	•	•	•	•		•	•	•	•	Contrast:	Þ.0 %
1							•			•	·	•		•		•	•	•	•	•	٠		Gain:	93.0 %
											.												G Gain:	13.0 %
2																							B Gam: U	13.0 %
		-	•	*		*	•		*	•	•	*	•	•	*	•	•	•	•	•	•	•	Explosure: 0	26.0
D		•	•	•	·		•	•	•	•	·	•	•	•	·	•	·	•	·	•	·	•	Continuous AE Target:	50.0 %
													DVisi	on Cali	bratic	on succ	ess!						Wait time(ms): 0 Color mode Rotate angle: 0 Comera fixed mod	de
					•		*				•		-		庸定	5		·		·	·	•	Camera calibration	
			•					*			•		•	•	•	•				·	·	•	1 Speed: 100.0 mm/s Power:	30.00 %
	•										•		÷			·	-	·	·	·	·	•	2 Width: 100.0 mm Height:	100.0 m
5	•	•	•			•					·			•	·				·	•	·	•	Speed: 100.0 mm/s Dot power:	30.00 %
18	•	·	•	•	•			•			•			•		·		·	·	·	·	•	Go scale Dot para Dot C	orrect
	٠	•	•	•	•	•					•					•						•	3 Redo 1st step Cut cross	
-	•	•	•	•	•		•													•			Manually correct offset(Not recommended) X: 0.000 mm Y:	0.000 m
										1000	C	3	•	11mm	•	C	a	m	e	R	<u>a</u>		Ratio: 1.000 <<< Reset SaveAs	Load

If calibration is successful, system prompt will pop up "calibration success"; If failed, the system prompts "calibration failure". So you need to calibrate repeatedly until success.

Note: After dotting calibration, suggested that do "camera distance calibration" again.

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Camera parar	n				4
Contrast:		-0	5	þ.o	%
Gain:				93.0	%
G Gain:	-0-			13.0	%
B Gain:	0			13.0	%
Saturation: *			-0	80.0	%
Explosure:	-0	-		26.0	%
Continuous	s AE		Target:	50.0	%
Camera calibr	ation 100.0	 ]mm/s	Power:	30.00	%
Camera calibr	ation 100.0	] mm/s	Power:	30.00 Calibration	%
Camera calibr 1 Speed: 2 Width:	ation 100.0		Power: Cut cross	30.00 Calibration	% 1
Camera calibr 1 Speed: 2 Width: Speed:	ration 100.0 100.0 100.0	mm/s	Power: Cut cross Height: Dot power:	30.00 Calibration 100.0 30.00	% 1 
Camera calibr 1 Speed: 2 Width: Speed: Go scale	ation 100.0 100.0 100.0	mm/s mm mm/s para	Power: Cut cross Height: Dot power:	30.00 Calibration 100.0 30.00 Correct	% ] ] 
Camera calibr Camera calibr Speed: Width: Speed: Go scale Redo 1st	ation 100.0 100.0 100.0 Dot p	mm/s	Power: Cut cross Height: Dot power: Dot	30.00 Calibration 100.0 30.00 Correct	% ] 
Camera calibr Camera calibr Speed: Go scale Redo 1st s Manually o	ation 100.0 100.0 100.0 Dot p step Cut	mm/s mm mm/s para cross	Power: Cut cross Height: Dot power: Dot	30.00 Calibration 100.0 30.00 Correct	່% ] 
Camera calibr Camera calibr Speed: Width: Speed: Go scale Redo 1st Manually o X:	etion 100.0 100.0 100.0 Dot p step Cut correct o 0.000	mm/s mm mm/s para offset(No	Power: Cut cross Height: Dot power: Dot Dot Y:	30.00 Calibration 100.0 30.00 Correct d) 0.000	% n %
Camera calibr Camera calibr Speed: Width: Speed: Go scale Redo 1st s Manually o X: Ratio:	ation 100.0 100.0 100.0 Dot p step Cut correct o 0.000 1.000	mm/s mm mm/s para cross offset(No mm	Power: Cut cross Height: Dot power: Dot ot recommende Y:	30.00 Calibration 100.0 30.00 Correct d) 0.000	%   mm   %

**[X]**, **[Y]** This parameters setting is to compensate the camera distance.

**(**Ratio **)** There is tiny difference in height between the calibration and the actual matched plane. You can improve cutting precision by this parameter.

Notice: When calibrated many times, cutting precision still cannot meet the user needs, you can adjust parameters of **[X]**, **[Y]**, **[**Ratio **]** manually in step 4.



#### 4.2.3 Calibration file management

Camera parar	n				
Contrast:		0		0.0	%
Gain:	-0			25.0	%
Explosure: "	-0-			20.0	%
Continuous	AE		Target:	50.0	%
		Stab	ilization time:	300	ms
Camera calibr	ation				
1 Speed:	100.0	mm/s	Power:	30.00	%
		(	Cut cross	Calibrat	ion
2 Width:	100.0	mm	Height:	100.0	mm
Speed:	100.0	mm/s	Dot power:	30.00	%
Go scale	Dotp	bara	Dot	Correc	ct
Redo 1st :	step Cut	cross			
Manually d	correct o	ffset(No	ot recommende	ed)	
X:	0.000	mm	Y:	0.000	mm
Ratio:	1.000	<<<			

**[**Save As **]** : After calibration successfully, the user can "save as" to save the calibration files under the specified directory, and set the file name. Interface as shown in below figure:



Save as		? 🔀
保存在 (L):	🔁 आंद्र 🔽 🥥 👔	• 🗹 😏
文件名 00):		保存(5)
保存类型 (T):	Calibration files(*.cor)	TD 当
		-48.18

**[Load]** : In normal circumstances, there is no need to do calibration operation every time by software. Users can load the existing calibration file, to implement calibration function.

When the camera and the machine position are unchanged, just need to load the existing calibration file. Click "load file", pop up a file dialog box to find the file need to calibrate, and click "open" button to complete loading operation. Interface is as follows:



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Open		? 🔀
查找范围(L):	🗁 බුය 🔽 🕑 🗊	📂 🛄 •
🗖 calibratio	on. cor	
-		
文件名 (M):	calibration	打开(0)
文件类型 (I):	Calibration files(*.cor)	取消
	□以只读方式打开 (图)	

**[Reset calibration ]:** When the camera calibrated, the results are not proper. Users need to correct again. Before the next correction, user must clear the calibration object. Then click the "Reset" to clear the calibration object.



# **Chapter 5 Model Management**

# 5.1 Create Model

Move the center of camera view to the actual image center, then click [Create] button, system will prompt user to enter a model name, as below figure showed:

保存模板	
模板名称:	
ОК	Cancel

Enter a non-existent model name, then click **[**OK **]**, a model has been created successfully.

# **5.2 Extract Features**

#### 5.2.1 Select Feature Region

The model editing mode switch button, which can be switched between "feature edit mode "and "Cutting edit mode".

In "feature edit mode", press the right mouse button, dragging to draw a green rectangle (can draw multiple times). The green rectangle area is feature region.

Notice of feature region selection:

Graphics of the feature region, it must be a unique identifier of the unit target object.

In the feature region, the color of Graphics and background must be different.

The larger the feature region, the longer the matching time. So don't choose too large region.

If big splicing model, the feature region cannot be located on the splicing backlash.

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### 5.2.2 Set Model Parameters

lodel s	ettings		
NO	Name	Worked count	Save image
<b>V</b> 1	1	0	Clean count
			Clean all
			Sel all
			Invert
			Delete
			Del all
Cr	eate [	Open	Save
C 0	ору	Splicing	Import image
	创建特殊	<b>ķ模板</b>	
Model s	etting		Advance
@ Fea	ture1 () Fe	ature2 () Feature:	3 🔿 Featur
Fea Sn	ture1 () Fe	ature2 () Feature:	3 () Featur 
Fea Sn Si	ture1 O Fe nooth:	ature2 Feature:	3 Featur - 80.0 % ap: 20.0 %
Fea Sn Si	model Noi ture1 O Fe mooth: milarity: 50. Angle: 180	ature2 () Feature:	3 () Featur 
Fea Sn Si Mat	model Noi ture1 O Fe mooth: milarity: 50. Angle: 180 ch num: 1	ature2 () Feature:	3 () Featur 

**[**Smooth coefficient ]: The higher the smoothing coefficient, the less the scattered points of feature region be extracted. (Detailed Description please refer to chapter 5.2.3).

**[Similarity]:** The matching scores of model and actual graphic, the higher the scores, the more the similarity. The similarity setting directly affects the matching quality.

**(Overlap]**: The overlap percentage of two target object envelope rectangular. This parameter controls whether targets can be identified when overlapping.

**[ Match Angle ]:** The model rotation and searching angle range. For example, the value set to  $180^{\circ}$ . In the matching process, the searching angle range is  $-180^{\circ} \sim 180^{\circ}$ . To set the search angle according to actual needs. The larger searching angle, the longer matching time required. If the user does not need to set this parameter, and you should remove the option.

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As shown in the following figure, there are two opposite triangles. If use a model matching, you must enable the

match angle and set the search angle as 180° Angle: 180.0 ° 🔽.

So that finding the two opposite triangles

when matching. However, in the process of rotation match, increase the amount of calculation and slowing the speed of matching. And reducing the matching accuracy at a certain. Therefore, in this case, it is recommended that using multi-model to match.



**(**Match test **)**: Match the current model and the target image of camera field view, test results will be returned as results-interface. When the matching results are not satisfied, adjust the similarity until the matching results satisfied.

#### **5.2.3 Feature Processing**

As shown in below figure, the red lines in the green rectangular box are feature curves. There are some excessive scatter-point or curves, user can improve the smooth coefficient to reduce the number of feature curves.

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If users want to delete some curves, in "features edit mode", press down the left mouse button and drag to draw a rectangle, and select the curves need to be deleted. Then press the "Delete" to delete excessive curves.

**[**Screen Feature curves **]** In "features edit mode", click system toolbar icon **[Final**. Select feature curves which length is less than the setting value.

## 5.3 Model Edit

#### 5.3.1 Extract Feature Contour

First, select a edited model (check the model). Click the icon on toolbar. In "feature edit mode", the

top-left of main-view window will prompt: Model edit mode

Press down the right mouse button and drag to draw a rectangle, the red lines are feature curves. If the feature curves are not obvious enough, users can adjust the ambient brightness to make a clear outline of the image. Also can adjust smoothing coefficient, get better quality feature curves. As shown below:





#### 5.3.2 Edit Cutting Curve

**Contour ]** In "model edit mode", feature curves has been existed. Firstly select feature-curves, and then click system toolbar icon, generating cutting curve contour automatically. Then edit cutting curves contour in "cutting edit mode".

**[Manual Drawing Cutting Contour]** In "cutting edit mode", edit cutting curves please refer to section 2.4. The blue lines are the cutting curves. As shown below:

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**[Node Edit]** In "Cutting edit mode", click the node edit tool **[12]**, to edit. User can add nodes, delete nodes, and node drag in node edit mode.





Dragging node to change the graphical outline;

Double-click the left mouse button on the contour curve to add a node;

Double-click the left mouse button on the node to delete a single node; choose multiple nodes and press the "Delete" key to delete multiple nodes.

After editing, the picture as shown below:





User can adjust graphic outline by node edit. Graphic contour transformation processing can meet the user's needs. Details please refer to sections 2.6 and 2.9.

Support importing contour drew by other graphics software (AutoCAD, Adobe Illustrator, CorelDraw) drawn to the model. Details please refer to sections 5.3.3

#### **5.3.3 Import Cut Contour**

In "Cutting edit mode", import cut contour.

In "model cutting mode", click [File] -> [Import], "open file" dialog box appeared. Next select the file and then click [Open]. As shown below:



Import		? 🗙
查找范围(I): 🔁	🔁 jff视觉测试20130410 🛛 🕑 🕜 🌮 🖽 🗸	
☐操作说明书1304 ☐ 11. ai ■ Contour. dxf	0418 ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓	
文件名(M): Conte	itour. dxf	Open
文件类型 (T): Supp	oported Files	取消

Import file to the model, drag the contour curve to right position. Fine-tuning can also be achieved by the top, bottom, left and right keyboard keys. Details please refer to section 2.3

#### 5.3.4 Copy Cut Contour

You can do operation of copy the cut contour between different models.

First of all, select the cut contour curves and press down "Ctrl+C" in "Cutting edit mode" of model A. Then, switch to 'Model B', press down" Ctrl + V", the copy operation is completed.



#### <u>RDVision Laser Cutting Control Software Operation Manual</u> 5.3.5 Multi-models

In the same target image contains different graphics, this software provides multi-models matching-search function. Its implementation steps:

Firstly, create two models;

Secondly, checking two models at the same time when model matching.

There are two opposing triangles in the following figure.





Create two models as shown below:



Then, check two models can be achieved multi-models matching. In the actual matching process, the inverted triangle matches with the inverted model and the upright triangle matches with the upright model.



### 5.4 Contour and Layers

#### 5.4.1 Contour Output Parameters

In the same batch of graphics processing, the different graphics need to set different processing parameters. Processing parameter corresponds to the color layers. Layer parameters are the contour of output parameters. Layer parameters can be modified according to user needs. As shown below:





Load param	eters from	library
Layer: Is Output: Speed(mm/s): If Blowing: Processing Mode: Min Power(%) Max Power(%)	Yes 100 Yes Cut 30	Default
Seal: Open Delay: Close Delay:	0.000 0 V Laser t Advance	mm ms ms through mode

#### 5.4.2 Set Contour Layer

Different layers with different colors. Different layers have different parameters. In the output of the processing, different contours output in the same processing parameters, just all contours set to the same color (That the same layer).

Different contours output in different processing parameters, just set contours to different color (That the different layer).

[Set Contour Layer]:	In "Cutting edit mode",	, select the contour.	Click the layer button.	As shown below:
----------------------	-------------------------	-----------------------	-------------------------	-----------------

Note: For more details about layers, please refer to section 6.1.1



# **5.5 Splice Model & Multi-Features**

Firstly, click [Splicing], the follow dialog box appeared:

Sp	licin	ıg					
	0.000	0.000			1 1 1		
1:	0.000	0.000	Set point1		laser head positi		
2:	0.000	0.000	Set point2	Start	Stop	Update	Cancel

The splicing operation requires two coordinates of graph diagonal.

Secondly, move the center of camera filed view to upper left corner of graphic. Then click **[**Set point 1**]**. As shown below:

Thirdly, move the center of camera filed view to lower-right corner. Then click [Set point 2]. As shown below:



Fourthly: Click [Start], splicing results as shown below:



Fifthly: If need to update the local area, click the left mouse button and drag to select area need to update. And click the "Update" button.

Click "Ok" button when splicing completed. It will create a mode automatically.



Splicing graphics as follows:



**(**Multi-Features **)** For a larger model (Splice image), you can choose many of its features to locate. In the **(**Model type **)** parameter sets the number of characteristics: normal, 2 points, 3 points, 4 points.

Note: You can create Multi-Features mode by importing scanning graph, details refer to "5.11 Import Image".

## 5.6 Save Model

User need to repeatedly use the model. The model should be saved as model file. Click **[**Save**]** and enter file name, model will be saved automatically.

## 5.7 Open Model

User need to open model file, click (Open) and select the file that needs to open. Then click (Open) button on the open-dialog box.



# **5.8 Delete Model**

Select the model that needs to delete, Click [Delete] button that the model will be deleted.

## 5.9 Delete All Model

This operation button will delete all model, click [Del all] button that all model will be delete.

### 5.10 Save Model Image

Save the model image as a picture file, the picture file can be imported into other graphics software. Draw Cutting contour and save it as a data file. Our software provides import operation for cutting contour data.

# 5.11 Import Image

Splice larger image, also can use scanner to scan the larger image. Click the 【Import Image】 function button to import scanning graph and create Multi-Features model.



# **Chapter 6 Processing Management**

# 6.1 Set Processing parameters

#### 6.1.1 Layer Parameters & Layer Button

Layer	Mode	Speed	Power	Output	
	Cut	10.000	30.000	YES	Layer list
					Layer butt
Enable f	eeding				
Feeding	num: 1	Feeding	length: 50	0.0 mm	
Feeding sp	eed: 100.	omm/s	Feeding af	ter processing	
Path opt	imize				
Path opt Block he	imize ight: 20.0	mm 🔽	Inside to c	utside	
Path opt Block he	imize ight: 20.0 Dir: Up to	mm 🔽	]Inside to c	utside	
Path opt Block he Match	imize ight: ½0.0 Dir: Up to num: 100	mm 🔽	] Inside to c	utside ch mode	
Path opt Block he Match Time	imize ight: ½0.0 Dir: Up to num: 100 eout: 300	mm 🔽	] Inside to c ] ] Speed mat	utside ch mode	

**[Layer List]:** Display layers parameters.

**[Layer Button]:** Select the curve that needs to set layer color, and then click layer button. It can set layer color. **[Modify Layer Parameters]:** When modify the layer parameters, double-click the left mouse button the corresponding row in the layers list. It will appear layer parameter dialog box.



Load parame	eters from I	ibrary
Layer:		1
Is Output:	Yes	-
Speed(mm/s):	100	Default
If Blowing:	Yes	-
Processing Mode:	Cut	-
Min Power(%)	30	Default
Max Power(%)	30	
Seal:	0.000	mm
Open Delay:	0	ms
Close Delay:	0	ms
	Laser t	hrough mode
	Advance	e
Ok		Cancel

User can modify the parameters in the "Layer parameter" dialog box. You can load parameters from parameter library if parameters file have been saved, previously.

Click [Load parameters from library], appears follow dialog:



Load parameters from lib	ary 🛛 🛛	
Parameters library: Default	Layer:Is Output:Yes If Blowing:Yes Processing Mode:Cut Speed:100.0 Laser1:30.0%30.0% Laser2:30.0%30.0%	Add parameter           Parameter name:         Default         Parameter note:
01	Save as Delete Load Exit	Ok Cancel

Select parameter file from the library, and then Click [Load], complete the parameters load operation.

You can also save current parameter to file. Click [Save as], and then enter the parameter name and parameter note.

If you want to delete a parameter file, you can select the file and click [Delete].



#### 6.1.2 Feeding

Layer	Mode	Spee	d Power	Output
	Cut	10.00	0 30,000	) YES
	eeding			500.0
			the second se	
Feeding	num: 1	Feed	ding length:	500.0 mm
Feeding sp	peed: 10	0.0 mm/s	ding length: [	after processi
Feeding sp	timize	0.0 mm/s	ding length:	after processi
Feeding sp Peth op Block he	timize	.0 mm	ding length: [ Feeding	after processi
Peeding sp Feeding sp Path op Block he	timize eight: ½0 Dir: Up	0.0 mm/s	ding length: Feeding Inside to	o outside
Feeding sp Path op Block he Match	inum: 1 beed: 10 timize sight: 20 Dir: Up num: 10	0.0 mm/s	ding length: Feeding Inside to	o outside
Peeding sp Path op Block he Match Tim	timize eight: 20 Dir: Up num: 10 eout: 30	0.0 mm/s	ding length: Feeding Inside to	o outside

**[Enable feeding]:** Automatic feeding

**[Feeding num]:** Set the number of feeding.

**[Feeding length]:** Set the length of feed each time.

**[Feeding speed ]:** Set the speed of feed.

**[**Feeding after processing ]: All processing are completed, whether user needs to feed. If you need, check this option. If no, do not check this option.


<u>RDVision Laser Cutting Control Software Operation Manual</u> 6.1.3 Path Optimize

Layer	Mode	Speed	Power	Output
	Cut	10.000	30.000	YES
Enable i				
Feeding sp	peed: 100.	mm/s	Feeding af	ter processi
Feeding sp	peed: 100.1	mm/s	Feeding af	ter processi
Feeding s Feeding s Path op Block h	timize	mm/s	Feeding af	utside
Feeding s Feeding s Path op Block h	timize eight: 20.0 Dir: Up to	mm/s	Feeding af	utside
Feeding sp Feeding sp Path op Block he Match Tim	timize sight: \$0.0 Dir: Up to num: 100 eout: 300	mm/s	length: 500   Feeding af   Inside to o	utside utside

**[Path Optimize]:** Only local optimize the matching data results once.

**[Block height]**: Optimize the processing data, the block can reduce the difficulty and optimization efficiency. The overall data is divided into a plurality of partial data blocks according to the block-height. In the optimization, the local data block as a unit for optimization.

**(Inside to outside ]:** If there is inclusion relationship in the cutting path, user can set the processing path to "inside to outside". (check "inside to outside").

**(Dir)**: In the path optimization processing, the direction of setting is the overall path direction.



## 6.1.4 Speed Match Parameters Setting

Layer	Mode	Speed	Power	Output
Enable fr	eedina			
Eeedina	oum: 1	Feeding	length 50	0.0 mm
record	nunn -	- recurry	nengun.	
Ecoding on	and 100.0	made	Deadled of	hav avacation
Feeding sp	eed: 100.0	mm/s	Feeding al	ter processing
Feeding sp	imize	mm/s	Feeding al	ter processing
Feeding sp Path opt Block he	imize ight: 20.0	mm/s	Feeding al	ter processing
Feeding sp Path opt Block he	imize ight: 20.0 Dir: Up to	mm/s	Feeding al	iter processing outside
Feeding sp Path opt Block he Match i	imize ight: 20.0 Dir: Up to num: 100	mm/s	Feeding al Inside to c	iter processing outside cch mode
Feeding sp Path opt Block he Match I Time	eed: 100.0 imize ight: 20.0 Dir: Up to num: 100 eout: 300	mm/s	Feeding al Inside to c	iter processing outside cch mode
Feeding sp Path opt Block he Match i Time Search t	imize ight: 20.0 Dir: Up to num: 100 eout: 300	mm/s	Feeding al  Inside to c    Speed mal	iter processing outside .ch mode

[Match num] In the effective filed of camera view, t he total number of existing matching-object.

**【Timeout】** When you set the parameter of 'Match num', you need to set this parameter to control matching time. In process of matching, in order to avoid waiting for a long time or lacking of time to cause the failure of target image matching. This parameter is mainly affected by the model characteristics of complexity and the target quantity.

**(Speed match mode)** When select this option, system will take fast algorithm in process of target-matching. Notice: when select the option Speed match mode', the Model parameters option 'Angle' must disable.

[Search type] Define searching type. Options include "Standard array", "Custom angle", Dynamic search. It

	Num	Offset	Dislocation		
X:	1	10.000	0.000	Custom	
Y:	1	10.000	0.000	Path Browse to wo	ork

combines with



# **6.2 Processing Status Parameters**

- X: The laser head current position on the X-axis
- Y: The laser head current position on the Y-axis
- U: The laser head current position on the U-axis

Total T:000:00:00:000:Single T:000:00:00:000:Work num: X:78.759mm, Y:48.949mm

**(Total T]:** The total time of processing workpiece.

**(Single T):** The time of processing one workpiece.

**[Work num]** : The total number of processed workpiece.

[Clear work info]: Click [Work Para] -> [Clear work info], reset the time and work num zero.

# **6.3 Set Processing Format Parameters**



- **[Num]** : Specify the search target number to match. You can specify the number of graphics on X-axis and Y-axis direction.
- **(Offset)** : The distance of each move on axis direction. The offset in the X axis direction is the column spacing. The offset of the Y direction is the line spacing.
- **[ Dislocation ]**: There are lines dislocations or column dislocation in array-graphics, you can set the X-Dislocation and the Y-Dislocation respectively.

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**[Position]** : Set current position-point as the machining-starting point.

**[Back]** The laser head moves back to the machining-starting point.

**[Path Browse]** Browsing matching-search path and view the camera zones.

**[Simulate]** Details please refer to section 6.5.1

**[Custom]** User defines search path, it can be nested custom search path.

When set "Array first", array path for systemic circulation, and the custom path for the minor cycle. When set "Custom first", custom path for systemic circulation, and the array path for the minor cycle.

Custon pat	h			
Enable custom	path	Array	first	~
NO	X	Array Custo	first m firs	
Delete	<b></b>	dd		115
	-	400		Up
Empty	M	odify		Down
Export	Im	port		Close



# **6.4 Devices Connect**

Appears follow dialog box:

Note:Please L	ink Machi	ne				
O USB	Auto					
	192 .	168	•	1	•	100
ОК			Ca	ncel	i.	

There are two device connect ways: USB and Web. Click [Device port] button, then set the connection ways and select connection port.

**【USB】**: If the computer is only connected to a laser device, you can set this option to automatically. The software will automatically determine the connection interface to the device. When the computer is connected to more than one laser equipment, you need to first click on the **【**Device Port **】** button. In the dialog box, click [Search] button. The search is completed, the drop-down list will be displayed the connected currently device interface. User selects the desired device interface, can output to the specified device.

**[Web]**: If the computer is only connected to a laser device, you can directly input IP address in the default device IP. When the computer is connected to more than one laser equipment, similar to the **[USB]**. Find the device has been connected, and select corresponding IP address of the device from the drop-down list.

# 6.5 Control single-axis motion, back to zero

### 6.5.1 Manually control single-axis motion

Single-axis motion control, you can only control one axis motion, you can set distance, speed of movement.







**(Stepping distance ]:** As shown: **v**, **fill out the step value in the edit box**. Single-axis movements, in accordance with the stepping distance move as a unit.

**[Speed]**: Set a single-axis movement speed, user-defined movement speed value.

# 6.6 Processing and Simulate processing

#### 6.6.1 Simulate processing

Processing data is ready, the user can simulate processing to preview machining results. Click [Simulate] button, starting the simulate processing. Click [Start / Pause] button to pause, click [Stop]] button to stop.

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6.6.2 Cut Test

Cut graphics at the current position. Click [Cut test] button.

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### 6.6.3 Processing

Confirmed the processing parameters are correct. Click **[** Start/Pause **]** button to process workpiece. Click **[** Start/Pause **]** button to pause, click **[** stop **]** button to stop.



**[Match test]** Details information please refer to 5.2.2



Thank you very much for using the product from Shenzhen RuiDa Technology!

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